

Development of the method of reconstruction of neutron energy spectrum with HGND in the BM@N experiment

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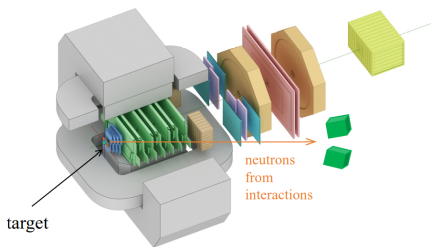


Outlook

- 1 BM@N
- 2 HGND
- 3 Clustering method
- 4 Background
- 5 Energy spectrum reconstruction
- 6 Conclusions

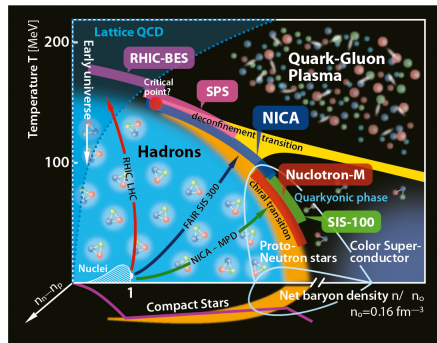
Baryonic Matter at Nuclotron

- Fixed target heavy-ion experiment at Nuclotron in Dubna, Russia
- Beam energy $2 - 6 \cdot A$ GeV
 - Study of hadronic matter at high baryonic densities



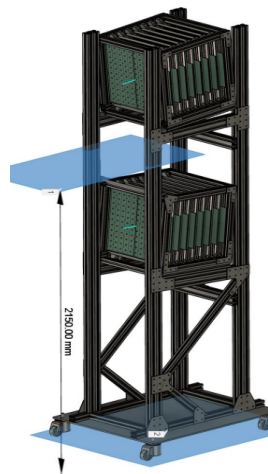
Physical motivation

- Need to study isospin degree of freedom of baryonic matter equation of state
- Neutrons are sensitive to isospin
- Absence of data on neutron yields at $1 - 10 \cdot A$ GeV



Highly Granular Neutron Detector

- New time-of-flight detector for measurements of neutrons with kinetic energy $T_n \lesssim 4$ GeV
- Alternating plastic scintillator/copper layers
- MPPC directly connected to scintillators
- Time resolution $\sim 150ps$
- High granularity enables precise neutron tracking

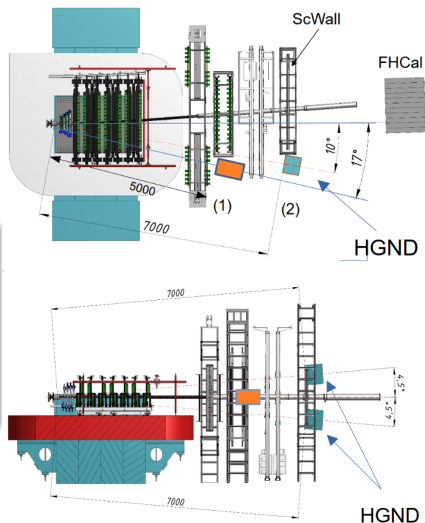


MC Simulation

In order to develop and check the algorithm of neutron identification the MC simulation was performed

Simulation parameters

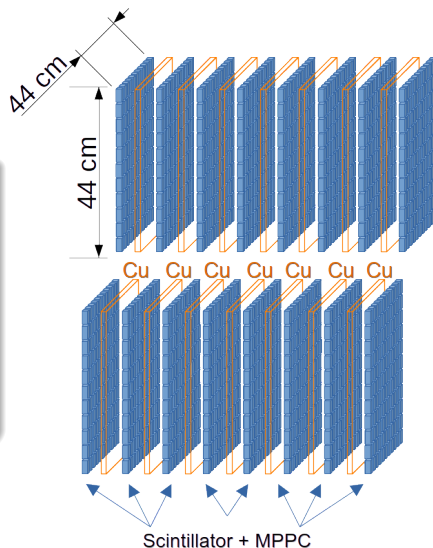
- Bi+Bi at $3 \cdot A$ GeV
- 200 000 events
- DCM-QGSM-SMM model
- Full BM@N geometry



HGND configuration

HGND parameters in simulation

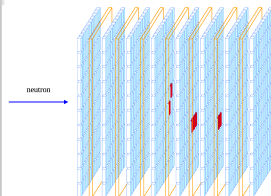
- Two parts mode
- 8 layers of scintillator 11x11 cells
- 7 layers of Cu convertor in between of scintillator layers
- Time resolution $130ps$



Clustering method

Algorithm

- ① Select cells with $E_{kin} > 3MeV$ (noise rejection)
- ② Merge neighboring cells into clusters
- ③ Calculate $\beta = \frac{1}{c}d/t$ for each cell; the cell with the highest β is labeled as the cluster "head"
- ④ Apply selection criteria



Selection criteria

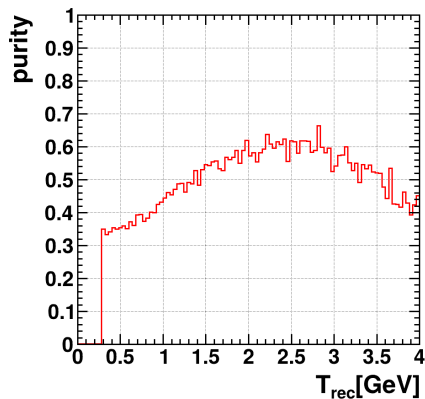
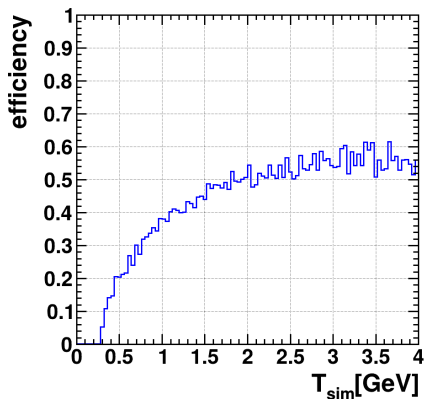
- No hit in layer 0 (charged particles rejection)
- No hit in layer 1 (γ rejection)
- $\beta < 0.9$ (fast e^+ , e^- , γ rejection)
- $T_{reconstructed} > 300$ MeV (secondary neutrons suppression)
- Cluster size $N_{cells} \geq 2$

Reconstruction Quality

Performance Metrics

$$\text{Efficiency} = \frac{N_{\text{neutron match}}}{N_{\text{neutrons}}}$$

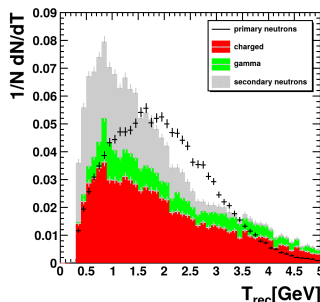
$$\text{Purity} = \frac{N_{\text{cluster match}}}{N_{\text{clusters}}}$$



Background contribution to the reconstructed energy spectrum

Background composition

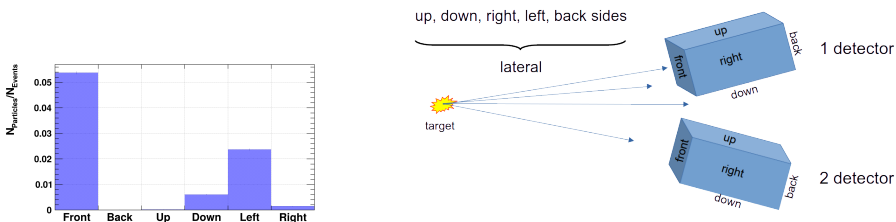
- Charged particles (mostly p , π^\pm)
- γ
- $n_{secondary}$ (produced or scattered in material)



Reconstructed energy spectrum of background particles vs. primary neutrons

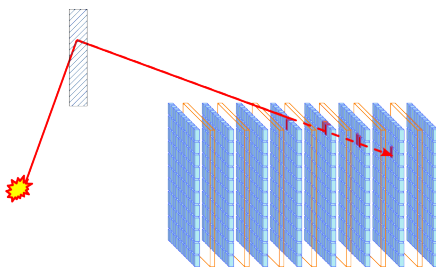
Charged particles

Charged particles produce clusters despite veto applied. Where do they come from?

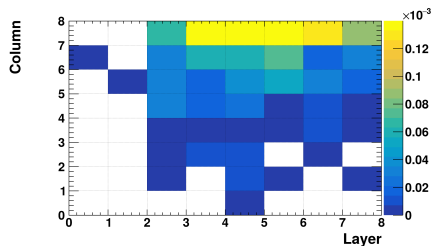
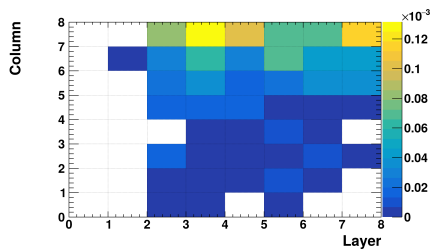


- ① Charged particles come through lateral sides
- ② Charged particles produce secondary clusters

1. Lateral hit

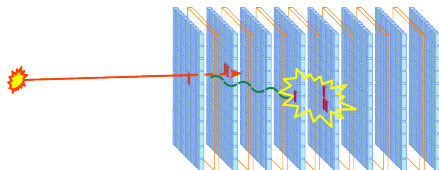


- The particle comes to the HGND through lateral surface
- First cell in cluster lies on border of HGND
- If cluster starts on border, we can reject it

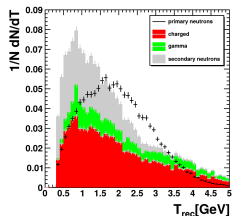


2. Secondary clusters

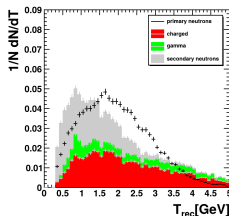
- p, π^+, π^- produce γ, n
- γ, n produce secondary clusters deep inside HGND
- There is a gap between primary and secondary clusters
- Secondary cluster is wrongly recognized as neutron
- The secondary cluster starts in the same (row, column) as hit in veto.
- We can reject such clusters



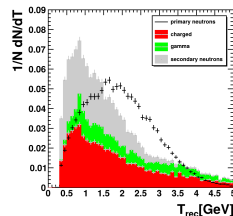
Background after new cuts



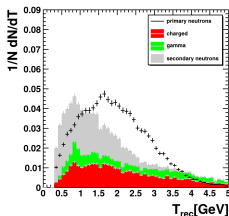
Basic selection



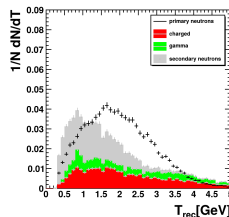
Border cut



Veto coincidence check



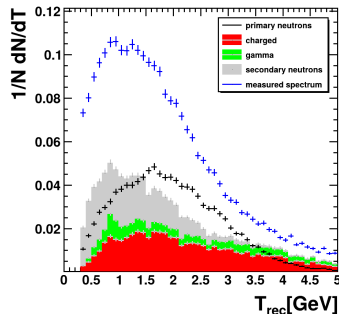
Border cut & veto coincidence check



Best cluster

Challenges

- After all cuts background remains comparable to signal
- Precise measurement of background is needed to subtract it
- Charged background can be measured by HGND itself
- Measurement of secondary neutrons and photons remains problematic
- Multiple corrections are needed:
 - Efficiency corrections
 - Multiple cluster corrections
 - Detector resolution effects



Subtraction of the background

The charged particle spectrum $f(T_{\text{rec}}) \equiv \frac{1}{N} \frac{dN_{\text{charged}}}{dT_{\text{rec}}}$ can be measured using the HGND veto layer.

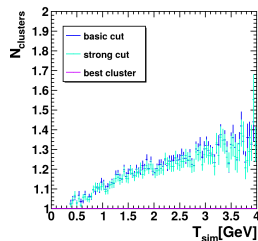
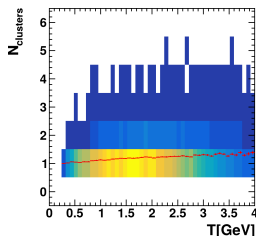
The probability $p(T_{\text{rec}})$ for a reconstructed cluster to originate from a charged particle can also be determined with HGND by analyzing time correlations between deep and surface clusters.

The charged particle background contribution $c(T_{\text{rec}})$ is then obtained via:

$$c(T_{\text{rec}}) = p(T_{\text{rec}}) \cdot f(T_{\text{rec}}) \quad (1)$$

Multiple clusters correction

- A single neutron interaction can generate multiple reconstructed clusters
- The mean cluster multiplicity $\langle N \rangle(T_n)$ depends on:
 - The clustering algorithm parameters
 - Neutron kinetic energy (T_n)
 - Impact position ($\bar{N}(\theta)$), $\bar{N}(\phi)$)
- This multiplicity distribution must be obtained from simulation



Resulting procedure of spectrum restoration

- 1 Clustering
- 2 Cluster selection
- 3 Distribution building
- 4 Background subtraction
- 5 Deconvolution
- 6 Efficiency correction
- 7 Comparison of the results obtained with different algorithms to estimate systematic uncertainty

Conclusions

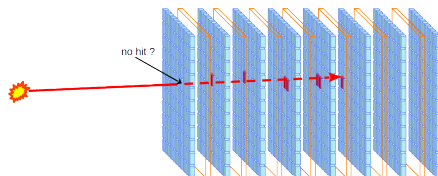
- Clustering algorithm for neutron identification in HGND has been developed
- Background comparable to signal requires sophisticated handling
- Multiple background rejection techniques have been implemented:
 - Basic cluster selection
 - Lateral particles rejection (border cut)
 - Secondary clusters rejection (veto coincidence)
- Afterward spectrum corrections are being developed:
 - Multiple clusters correction
 - Background spectrum subtraction
 - Deconvolution with detector response function

End

Thank you for your attention!

Front side

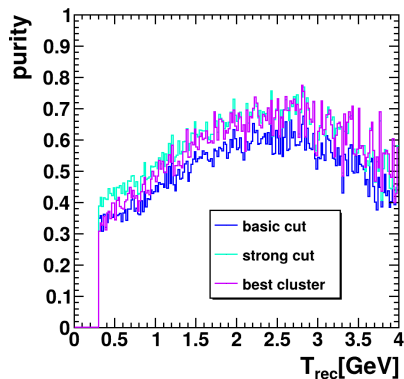
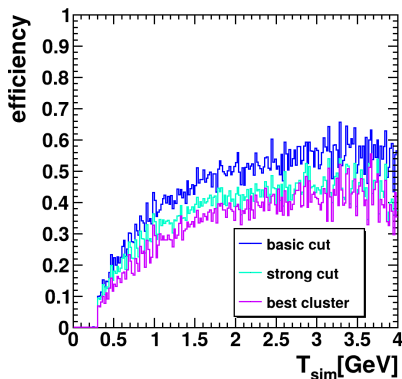
- Deposited energy below threshold (3 MeV)
- Particle pass in between cells, too low energy deposited in each cell
- Charged particle can't avoid hit in both veto and 1st layers, probability is negligible



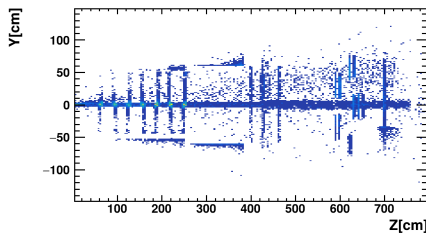
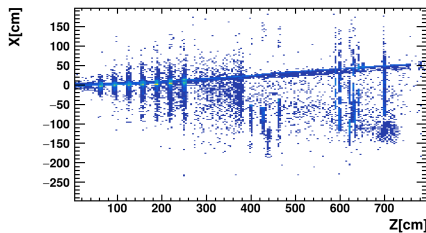
Quality after new cuts

Additional strict criteria improve purity but reduce efficiency. Strong cut:

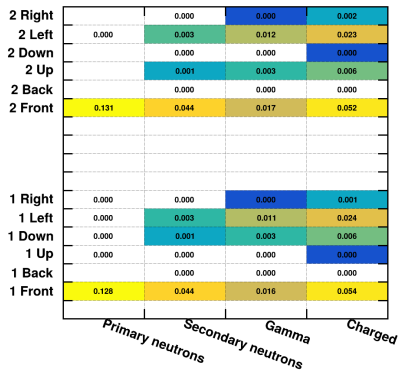
- Border cell rejection
- Veto layer coincidence check



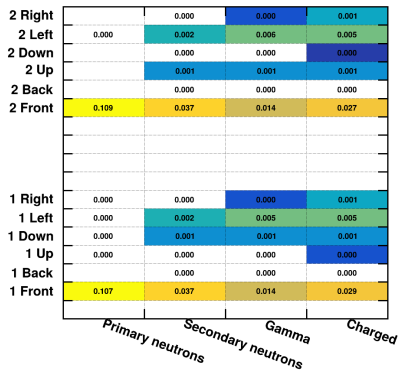
Background sources



Detector side vs. particle species



Basic selection



Border cut